# Wireless inertial sensor based objective lameness evaluation

### **Outline**

- Research studies –
   justification for
   objective evaluation
- Instrumentation
- Analysis
- Research studies –
   accuracy and
   reliability
- Indications
- Case examples





### **Justification**

2010 study from University of Missouri –

- 131 horses evaluated subjectively by 2-5 veterinarians with a weighted average of 18.7 years of experience
- After straight line evaluation, agreement on whether a limb was lame or not in 77%
  - 93% agreement if lameness grade > 1.5
  - 62% agreement if lameness grade  $\leq 1.5$
- After full lameness evaluation, agreement on whether the horse was lame and choosing the worst limb in 52%
- Conclusion: "For horses with mild lameness subjective evaluation of lameness is not very reliable"



### **Objective evaluation of lameness**

- Camera-based kinematic evaluation of movement on a treadmill
  - Requires carefully controlled lighting and background
  - Requires training of the horse to the treadmill
- Stationary force plate evaluation
  - Requires dedicated space and technical expertise
  - Sufficient data often requires multiple hoof strikes on the plate, which requires time and patience
- → Neither of these techniques are practical in a clinical lameness exam





### **The Lameness Locator**

• Indicates whether the horse is lame, which limb or limbs are affected, the severity of the lameness, and the part of the motion cycle at which peak pain is occurring (impact, midstance, or push off)



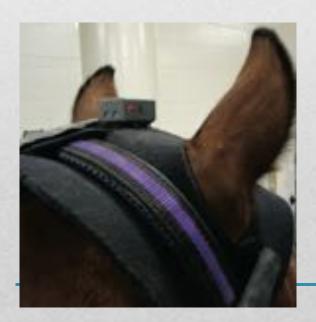


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### Instrumentation

- 3 wireless sensors: one on the horse's head, another on the center of the pelvis, and a third on the right front pastern
- Data sent wirelessly to a tablet computer for almost instantaneous analysis



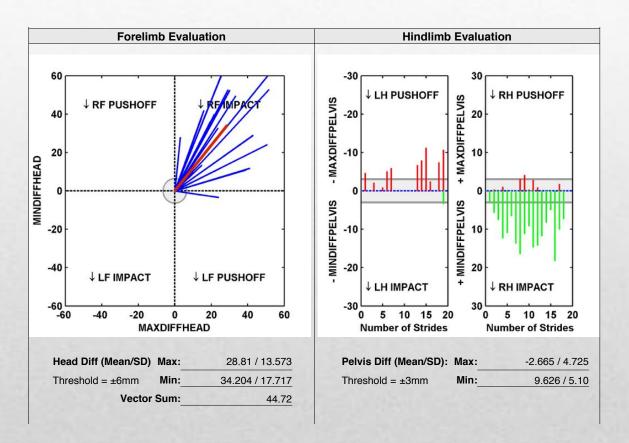




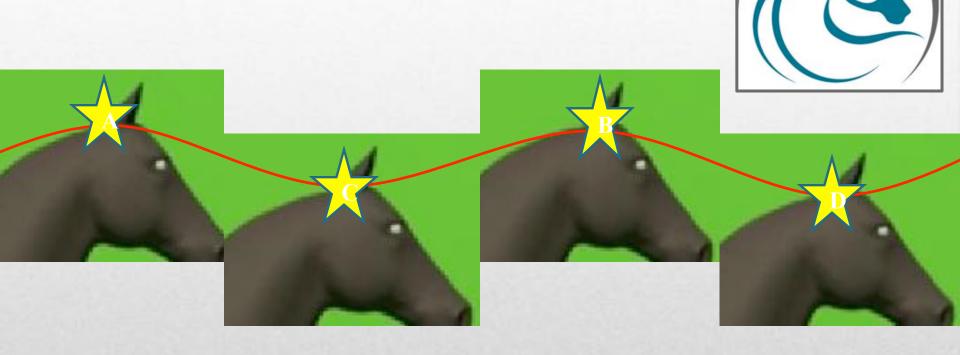


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- Vertical movement of the torso (which is measured by the sensors) will mirror vertical ground reaction forces
- Asymmetry in vertical torso movement between right and left halves of the stride can be quantified and associated with severity of lameness
- Sensors (accelerometers) on the head and pelvis measure and quantify the asymmetry



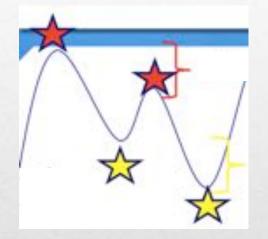




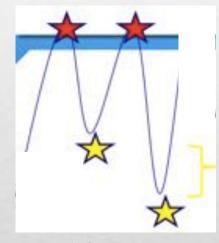
Maximum and minimum positions of the head

### **Basic Premise – head movement**

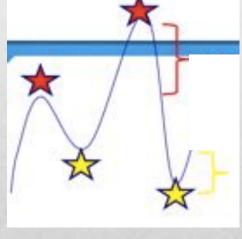




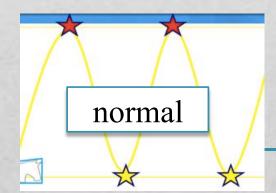
impact



mid stance

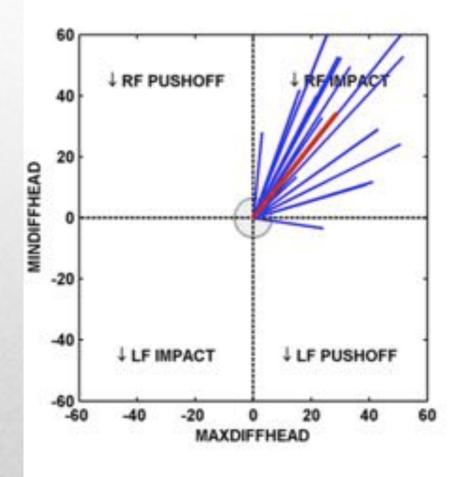


push off



### **Analysis**

#### Forelimb Evaluation



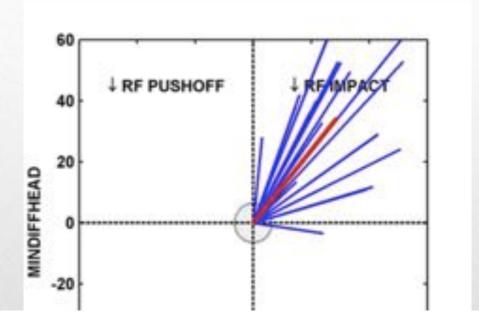


Head Diff (Mean/SD) Max: 28.81 / 13.573
Threshold = ±6mm Min: 34.204 / 17.717

Vector Sum: 44.72

**Analysis** 





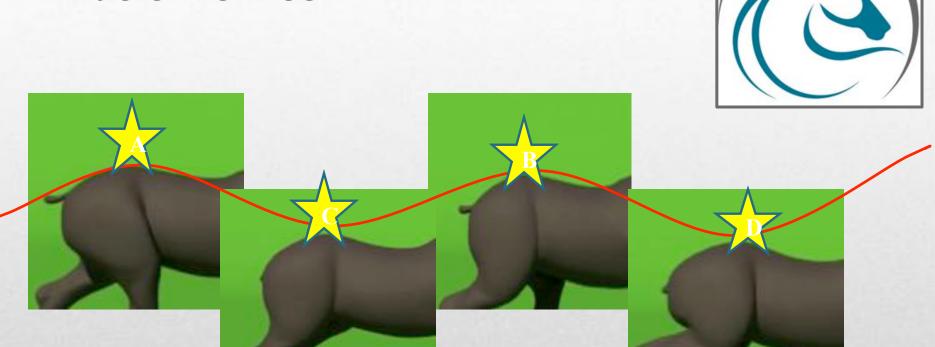


Head Diff (Mean/SD) Max: 28.81 / 13.573

Threshold = ±6mm Min: 34.204 / 17.717

Vector Sum: 44.72

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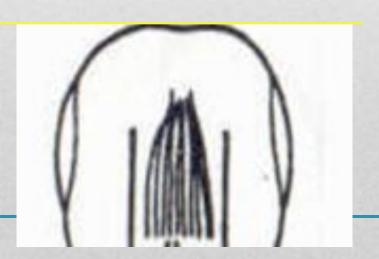
Maximum and minimum positions of the pelvis

### **Basic Premise – pelvic movement**

Maximum height

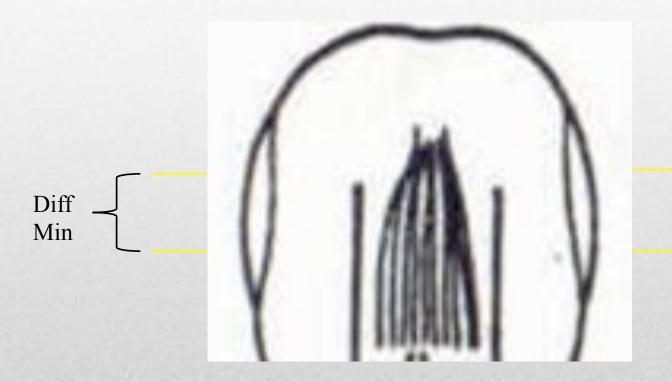


Minimum height



### Basic Premise – RH impact lameness





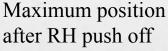
Minimum position during RH stance

Minimum position during LH stance

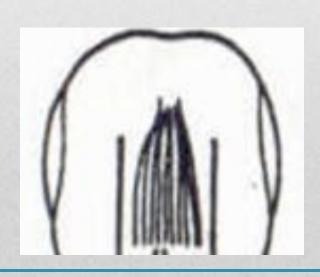
### Basic Premise – RH push off lameness



Maximum position after LH push off

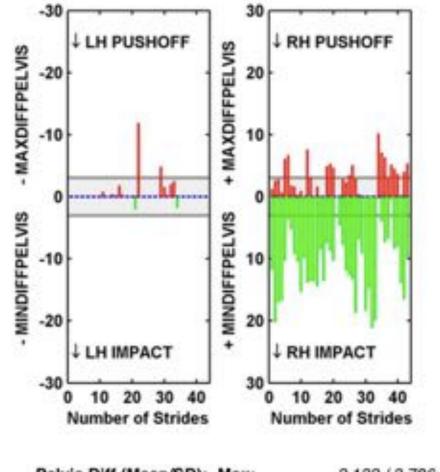






### **Analysis**

#### **Hindlimb Evaluation**



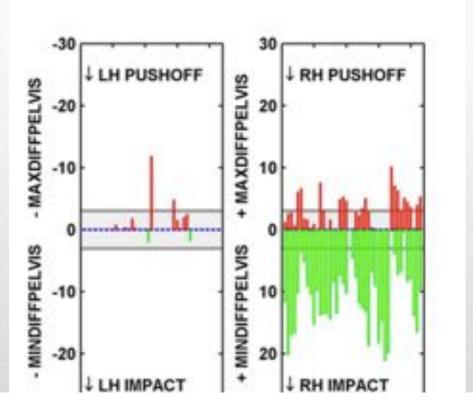


Pelvis Diff (Mean/SD): Max: 2.132 / 3.786

Threshold =  $\pm 3$ mm Min: 10.769 / 5.551

### **Analysis**

#### Hindlimb Evaluation



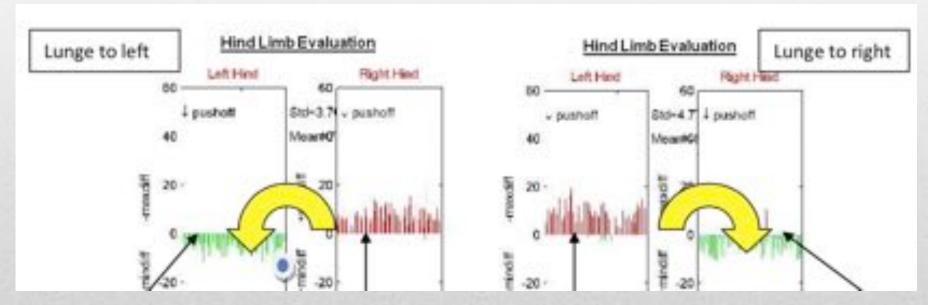


Pelvis Diff (Mean/SD): Max: 2.132 / 3.786

Threshold =  $\pm 3$ mm Min: 10.769 / 5.551

### **Analysis - Lunging**





### **Multiple Limb Lameness**



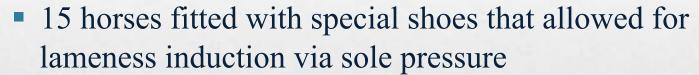
- Secondary lameness
  - Actual pain that occurs as a result of overload on the other limbs
- Compensatory lameness
  - Shifting of weight that only appears to be lameness (more common)
  - Subtle primary hindlimb lameness can cause compensatory forelimb lameness on the same side (left hind; left front)
  - Severe primary forelimb lameness can cause compensatory hindlimb lameness in both hindlimbs

### **Research - reliability**

- On two consecutive trials, coefficient of variation was 14-17% (force plate analysis is <10%); this was considered sufficiently repeatable for clinical use
- Compared with force plate, correct classification for head movement asymmetry was 83%; this was considered to be adequate sensitivity for clinical use



2012 study from University of Missouri









- 4 episodes of lameness induced in each horse, for a total of 60 lameness inductions over the 15 horses
- Evaluators (3 experienced equine practitioners) were blinded to the limb, the location of the screw, and the other evaluators' results
- Each trial:
  - Baseline evaluation in a straight line twice
  - Successive additional evaluations in which the screw was sequentially tightened an additional half turn
  - Successive evaluations repeated until lameness of the selected limb detected by all three evaluators and the sensors



- Results:
  - The inertial sensors selected the correct limb sooner (after fewer turns of the screw) than the consensus of 3 subjective evaluators
  - The inertial sensors selected the correct limb an average of one half-turn before the consensus of 3 subjective evaluators
  - Proportion of lameness chosen correctly first by:
    - Subjective consensus was in 8% of trials
    - Inertial sensors was in 58% of trials
    - Subjective consensus and inertial sensors at the same time was in 33% of trials

- Likely reason for higher sensitivity of the inertial sensors at detecting mild lameness is the higher sampling frequency (200Hz) compared with temporal resolution of the unaided human eye (15-20Hz)
- Conclusions:

"inertial sensor system was more sensitive than the consensus of 3 equine veterinarians"

# Research – comparing with subjective evaluation in naturally occurring lameness



2013 study from University of Missouri

- 106 horses evaluated by inertial sensors during trotting in a straight line, and then via subjective evaluation by 3 experienced practitioners who performed complete lameness examinations including lunging and flexions
- Evaluators agreed on classification into three categories (primarily right limb lameness, primarily left limb lameness, or equal right and left limb lameness) in 59% of forelimb lamenesses and 55% of hindlimb lamenesses

# Research – comparing with subjective evaluation in naturally occurring lameness



- All inertial sensor measures were positively and significantly correlated with subjective results
- Agreement between inertial sensors and subjective results was fair to moderate for forelimbs and slight to fair for hindlimbs
  - However, strong association would suggest that inertial sensor evaluation could not yield additional information
- Conclusion:

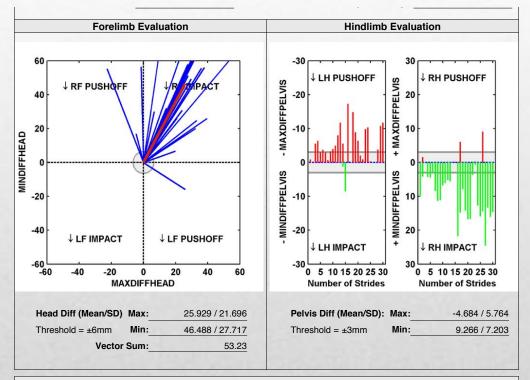
"inertial sensor-based evaluation may augment but not replace subjective lameness examination"

### **Specific indications**

- Subtle lameness
- Multiple limb lameness
- Compensatory lameness
- Nerve and joint blocks, especially in subtle lameness
- Rechecks or monitoring improvements during a rehabilitation program
- Useful as an adjunct to all lameness evaluations



# Case example 1 – straight line evaluation





#### **Evaluator Notes**

#### **Expert System Assessment**

There is "no" evidence of LF lameness.

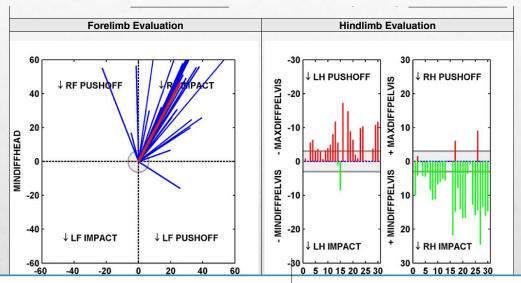
There is "strong" evidence of "severe" RF lameness.

There is "weak" evidence of "mild/moderate" LH lameness.

There is "strong" evidence of "moderate/severe" RH lameness.

These results may be indicative of a primary RF lameness.

### Case example 1 – straight line evaluation





Head Diff (Mean/SD) Max: 25.929 / 21.696

Threshold =  $\pm 6$ mm 46.488 / 27.717 Min:

> **Vector Sum:** 53.23

Pelvis Diff (Mean/SD): Max: -4.684 / 5.764

Threshold = +3mm Min: 9.266 / 7.203

**Expert System Assessment** 

There is "no" evidence of LF lameness.

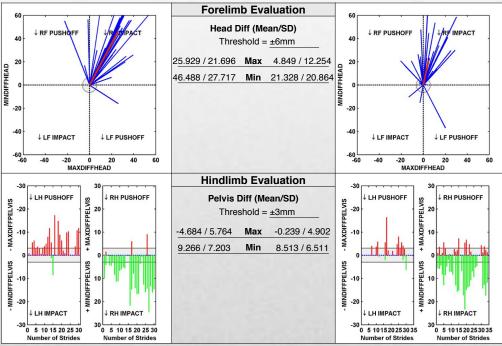
There is "strong" evidence of "severe" RF lameness.

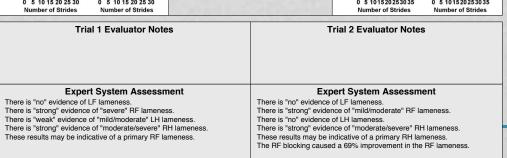
There is "weak" evidence of "mild/moderate" LH lameness.

There is "strong" evidence of "moderate/severe" RH lameness.

These results may be indicative of a primary RF lameness.

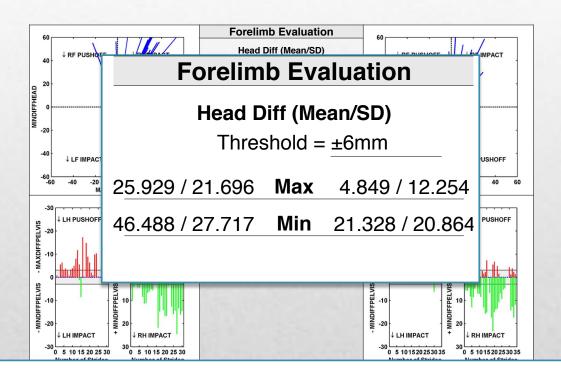
## Case example 1 – before and after nerve blocks







### Case example 1 – before and after nerve blocks





The RF blocking caused a 69% improvement in the RF lameness.

There is "strong" evidence of "severe" RF lameness There is "weak" evidence of "mild/moderate" LH lameness. There is "strong" evidence of "moderate/severe" RH lameness. These results may be indicative of a primary RF lameness

There is "strong" evidence of "mild/moderate" RF lameness.

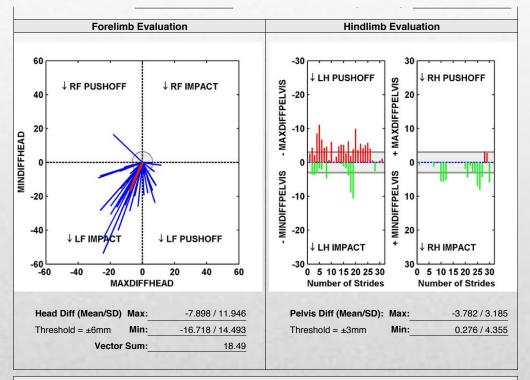
There is "no" evidence of LH lameness.

There is "strong" evidence of "moderate/severe" RH lameness

These results may be indicative of a primary RH lameness.

The RF blocking caused a 69% improvement in the RF lameness

# Case example 2 – first straight line evaluation





#### **Evaluator Notes**

#### **Expert System Assessment**

There is "strong" evidence of "mild/moderate" LF lameness.

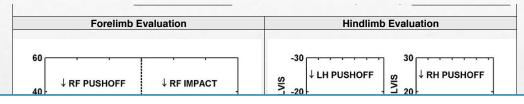
There is "no" evidence of RF lameness.

There is "strong" evidence of "mild" LH lameness.

There is "no" evidence of RH lameness.

There is insufficient evidence to suggest which limb is primary and which limb is compensatory.

# Case example 2 – first straight line evaluation





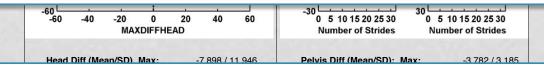
**Head Diff (Mean/SD) Max:** -7.898 / 11.946

Threshold =  $\pm 6$ mm **Min:** -16.718 / 14.493

Vector Sum: 18.49

**Pelvis Diff (Mean/SD): Max:** -3.782 / 3.185

Threshold =  $\pm 3$ mm **Min**: 0.276 / 4.355



#### **Expert System Assessment**

There is "strong" evidence of "mild/moderate" LF lameness.

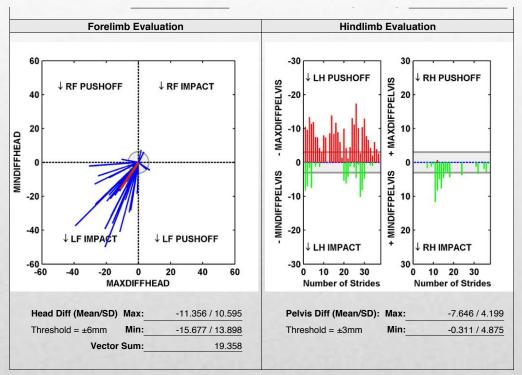
There is "no" evidence of RF lameness.

There is "strong" evidence of "mild" LH lameness.

There is "no" evidence of RH lameness.

There is insufficient evidence to suggest which limb is primary and which limb is compensatory.

# Case example 2 – second straight line evaluation





#### **Evaluator Notes**

#### **Expert System Assessment**

There is "strong" evidence of "mild/moderate" LF lameness.

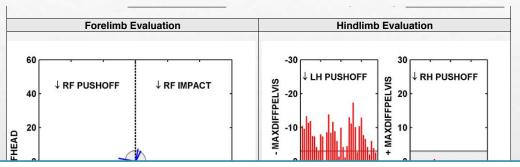
There is "no" evidence of RF lameness.

There is "strong" evidence of "moderate/severe" LH lameness.

There is "no" evidence of RH lameness.

These results may be indicative of a primary LH lameness.

# Case example 2 – second straight line evaluation





#### MAXDIFFHEAD

**Head Diff (Mean/SD) Max:** -11.356 / 10.595

Threshold =  $\pm 6$ mm **Min**: -15.677 / 13.898

**Vector Sum:** 19.358

**Number of Strides** 

-0.311 / 4.875

**Number of Strides** 

**Pelvis Diff (Mean/SD): Max:** -7.646 / 4.199

Threshold =  $\pm 3$ mm **Min:** -0.311 / 4.875

Threshold = ±6mm	Min:	-15.677 / 13.898	Threshold = ±3mm	Min:
Vector Sum:		19.358		

#### **Expert System Assessment**

There is "strong" evidence of "mild/moderate" LF lameness.

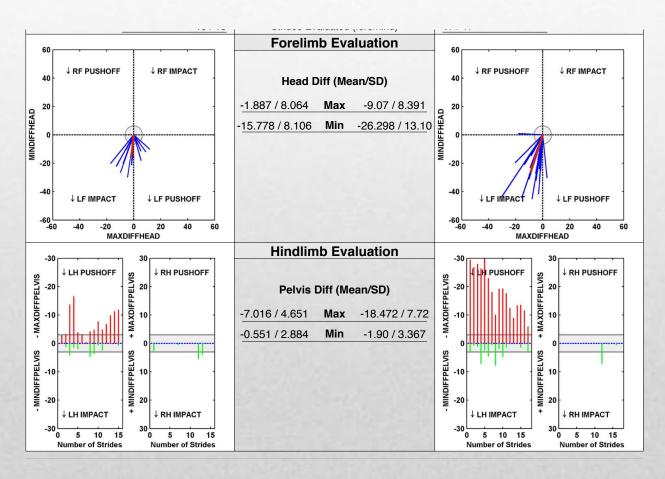
There is "no" evidence of RF lameness.

There is "strong" evidence of "moderate/severe" LH lameness.

There is "no" evidence of RH lameness.

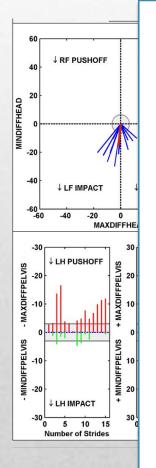
These results may be indicative of a primary LH lameness.

# Case example 2 – before and after hindlimb flexion





# Case example 2 – before and after hindlimb flexion



#### **Forelimb Evaluation**

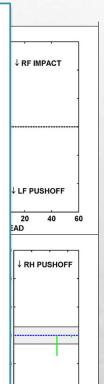
#### Head Diff (Mean/SD)

-1.887 / 8.064 **Max** -9.07 / 8.391 -15.778 / 8.106 **Min** -26.298 / 13.10

#### **Hindlimb Evaluation**

#### Pelvis Diff (Mean/SD)

-7.016 / 4.651 **Max** -18.472 / 7.72 -0.551 / 2.884 **Min** -1.90 / 3.367



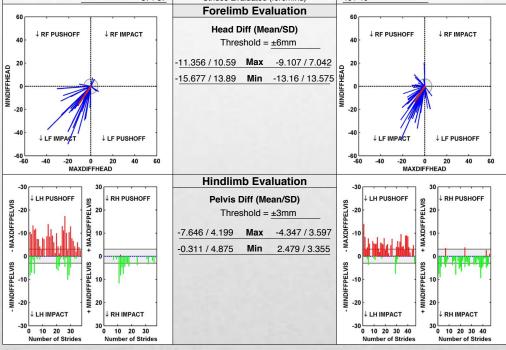
**↓ RH IMPACT** 

5 10 15

Number of Strides



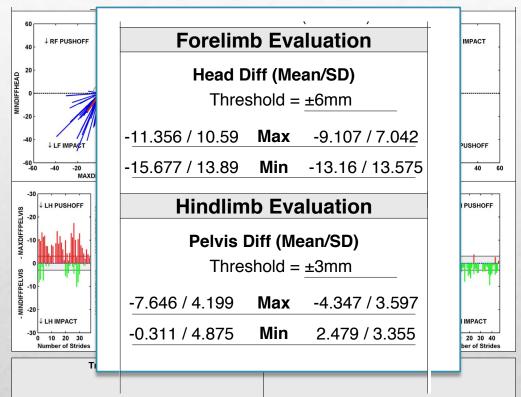
# Case example 2 – before and after joint blocks



Trial 1 Evaluator Notes	Trial 2 Evaluator Notes
Expert System Assessment  There is "strong" evidence of "mild/moderate" LF lameness. There is "no" evidence of RF lameness. There is "strong" evidence of "moderate/severe" LH lameness. There is "no" evidence of RH lameness. There is "no" evidence of RH lameness. These results may be indicative of a primary LH lameness.	Expert System Assessment There is "strong" evidence of "mild" LF lameness. There is "no" evidence of RF lameness. There is "moderate" evidence of "mild" LH lameness. There is "no" evidence of RH lameness. These results may be indicative of a primary LH lameness. The LH blocking improved the LH pushoff lameness by 71%.



# Case example 2 – before and after joint blocks





The LH blocking improved the LH pushoff lameness by 71%.

### References

- Equinosis inertial sensor-based objective lameness evaluation. http://www.equinosis.com. Accessed March 10, 2015.
- Keegan, K.G., et al. (2010). Repeatability of subjective evaluation of lameness in horses. *Equine Veterinary Journal* 42, 92-97.
- Keegan, K.G., et al. (2011). Assessment of repeatability of a wireless, inertial sensor-based lameness evaluation system for horses. *American Journal of Veterinary Research* 72, 1156-1163.
- Keegan, K.G., et al. (2012). Comparison of an inertial sensor system with a stationary force plate for evaluation of horses with bilateral forelimb lameness. *American Journal of Veterinary Research* 73, 368-374.
- Keegan, K.G., et al. (2013). Comparison of a body-mounted inertial sensor system-based method with subjective evaluation for detection of lameness in horses. *American Journal of Veterinary Research* 74, 17-24.
- McCracken, M.J. (2012). Comparison of an inertial sensor system of lameness quantification with subjective lameness evaluation. *Equine Veterinary Journal* 44, 652-656.
- Tyrrell, L. Understanding Max and Mins with ray plots.pptx. Accessed Feb 26, 2015.

